

Challenges and Solutions for Deep Learning Processors for Embedded Vision



Artificial Intelligence and Deep Learning



Artificial Intelligence

Machine Learning

Neural Networks

Deep Learning

- Artificial Intelligence
 - Human levels of intelligence exhibited by machines
 - Narrow AI: Technology outperforming humans in a narrowly defined task
- Machine learning
 - An application of artificial intelligence that uses algorithms to analyze large amounts of data and then infers some information about the real world from the data
- Neural Networks
 - A class of machine learning algorithms modeled after the human brain with a neuron representing the computational unit and the network describes how these units are connected to each other
- Deep Learning / Deep Neural Networks
 - A subset of machine learning using artificial neural networks with input, output and 'hidden' intermediate. Deep neural networks are capable of learning using large data sets



Embedded Vision Applications

- Surveillance cameras
- Automotive
 - ADAS
 - Autonomous driving
- Consumer
 - Drones
 - Smart Home / IoT
- Mobile
- Mixed/augmented reality glasses
- Image Super Resolution
 - Digital TV
 - Digital Still Camera



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Traditional Embedded Vision Pipeline

Pre-processing	Selecting Areas of Interest	Precise Processing of Selected Areas	Decision Making
 Noise reduction Color space conversion Gamma correction Image scaling Gaussian pyramid 	 Object detection Background subtraction Feature extraction Image segmentation Connected comp. labeling 	 Object recognition Tracking Feature matching Gesture recognition 	 Motion analysis Match/no match Flag events

- Mathematical approach to image analysis and interpretation
 - Extracting simple features: lines, edges
 - Integrating simple features into higher level features
 - Segmentation by simple analysis of localized pixels
- Shallow machine learning for classification

Traditional Embedded Vision Pipeline



- Complex, heterogeneous processing
- High performance required \rightarrow multi-core vector processing

DesignWare[®] EV6x Embedded Vision Processor IP

Scalable Hardware-Software Solution for High Accuracy Vision Processing



- Wide vector DSP processing
 - Supports full range of vision algorithms
 - Scalable from 1 to 4 vision CPU cores
 - EV64 delivers up to 990 GOP/s*
 - EV64 delivers up to 328 GMAC/s*
- High productivity standards-based toolset
 - OpenCV libraries, OpenVX framework, OpenCL C compiler, C/C++ compiler
- Supports requirements for traditional embedded vision processing
 - Pre-processing, scaling, region-of-interest selection, decision making

Traditional Computer Vision for Object Detection

Histogram of oriented Gradients (HoG) example

In the past, most pattern recognition tasks were performed on vector processing units with programs hand-tuned for feature extraction followed by shallow learning

Histogram of Oriented Gradients (HoG) Object appearance and shape within an image can be described by the distribution of intensity gradients or edge directions.





Recent EV Market Trends & Perspective

- Displacement of traditional vision algorithms with deep learning for improved accuracy
 - –i.e. Pedestrian Detection (HoG), Face detection (Viola-Jones)
 moving to Convolution Neural Network (CNN) based deep learning approaches
- Rapid evolution in deep learning technology to a wide set of applications



CNN-based Object Classification



Top 5 classes:

- 1: moped
- 2: motor scooter, scooter
- 3: barrow, garden cart, lawn cart, wheelbarrow
- 4: tricycle, trike, velocipede
- 5: crash helmet



Deep Learning Approaches Human Levels of Accuracy ImageNet Large Scale Visual Recognition Challenge Results





Yolo: Object Detection and Localization



Scene Segmentation



Source: Press Release by Toshiba and Denso, 17 Oct. 2016



CNN-based Denoiser





Super resolution using CNN \rightarrow 600 GMAC per 4K frame



"Image Super-Resolution Using Deep Convolutional Networks (2016), C. Dong et al."



Neural Networks for Radar Waveform Recognition



Figure 4. In this figure, we exhibit the processing with P3 code at an signal-to-noise ratio (SNR) of -4 dB.

- An automatic radar waveform recognition system to detect, track and locate low probability of intercept (LPI) radars.
- The detected signals are processed into binary images which are resized for CNN
- The finished binary images are used in CNN and feature extraction



Ming Zhang, Ming Diao, Lipeng Gao * and Lutao Liu http://www.mdpi.com/2073-8994/9/5/75



Emerging Embedded Vision Solutions

- Combining the best of traditional vision and deep learning approaches
- Combining scalar, vector processing with specialized CNN engine



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Choosing a Processor for Embedded Vision





DesignWare[®] EV6x Embedded Vision Processor IP

Scalable Hardware-Software Solution for High Accuracy Vision Processing



- Integration of traditional CV and CNN
 - Unified scalar, vector DSP and convolutional neural network (CNN) architecture
- High-performance, programmable CNN engine
 - Scalable from 880 to 1760 to 3520 MACs/cycle delivering up to 4.5 TMACs/sec performance*
 - Dedicated memory architecture
 - Dedicated DMA
 - Multi-dimension parallelism
 - Support of 8 bit and 12 bit data accuracy
 - Supports all modern CNN graphs (e.g., VGG16, GoogleNet Inception, ResNet, DenseNet, MobileNet, SqueezeNet, Yolo, Faster R-CNN, SSD, Denoiser, etc.)
- CNN mapping tool from well-known CNN frameworks, including Caffe and Tensorflow



Denoiser Filter Results

Close comparison of 12-bit and 8-bit accuracy





Summary

- Deep learning techniques, like convolutional neural networks, offer the highest accuracy for object classification, detection, and scene segmentation
- CNN replacing traditional computer vision algorithms
- Specialized CNN architecture offers area and power efficiencies, and higher accuracy for image quality improvement applications

DesignWare EV6x Processors



- Unified multicore processor for automotive vision processing
- Scalar + vector DSP + CNN engine
- State-of-the-art convolutional neural network (CNN)



Thank You

